

A Hierarchical Machine Learning Framework for Military Activity Recognition

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Summary

Human activity recognition (HAR) systems can help automatically identify movement patterns performed by military members, improving the military's ability to investigate movement-specific biomechanical outcomes. However, the accuracy of deep-learning methods for temporal data is limited by window and step sizes. We propose a hierarchical machine-learning framework to improve the classification accuracy of military tasks. Our framework's performance was compared to a deep convolutional long-short-term memory neural network (ConvLSTM). The hierarchical framework achieved higher accuracy and subsequence performance than the ConvLSTM model.

Introduction

Accurately labelling complex movements recorded as part of prolonged military training exercises is crucial for optimising and monitoring military task performance. Furthermore, segmenting sub-movements from large datasets of motion data enables military researchers to perform in-depth movement-specific assessments. Traditional methods, such as capturing movements in isolation or manually identifying movements within larger datasets, reduce ecological validity and are time-consuming. HAR systems offer an alternative by leveraging deep-learning models to classify movement patterns within large datasets using overlapping sliding windows. Military HAR models have previously been developed using a ConvLSTM model with data from a single IMU [1]. However, the model's accuracy depends on the window and step size. To overcome the accuracy limitations of the overlapping sliding window approach, we propose a hierarchical machine-learning framework that labels military movement patterns by combining change point detection, deep learning, and logic. The hierarchical model's performance was compared to a ConvLSTM model.

Methods

Thirty-three members of the Canadian Armed Forces completed military transition tasks while donning a 17-sensor inertial measurement unit suit (MVN Link, Movella, US; [2]) to record whole-body movements at 240 Hz. The tasks were manually labelled into sub-movements ($n = 29$). Each task contained between eight and 25 sub-movements.

A ConvLSTM was trained using segment accelerations, angular velocities, positions, and joint angles in 3D from all sensors. The dataset was separated following a 70:15:15 training, validation, and testing split. The model, containing four convolutional and two LSTM layers, was trained using an optimal sliding window of 240 and a step of 48 frames.

Results from the ConvLSTM were processed through a logical algorithm to ensure real-world constraint adherence.

A hierarchical machine learning framework was developed to automatically label sub-movements in a stepwise manner. Trials were first separated into static versus dynamic segments using a pruned exact linear time model. Static segments were classified as one of seven possible labels using a one-dimensional convolutional neural network, with label-specific adjustments implemented in the framework to correct start and end frames. Running segments were identified within the dynamic segments using the ConvLSTM model. A series of logical algorithms were then used to identify the dynamic transition sub-movements ($n = 21$) that connect the identified static or running segments (e.g., run-to-kneel, kneel-to-stand).

The performance of both techniques was evaluated using accuracy and F1 scores for each trial. Movement pattern sequences were compared to ground truth labels using the longest common subsequence method.

Results and Discussion

The hierarchical model outperformed the ConvLSTM model in labelling accuracy, F1-score, and movement pattern sequence identification (Table 1). The hierarchical model's strong ability to identify the correct sequence of movement patterns within a trial indicates that the predicted labels are congruent with the true movement patterns and contain no additional or missing movements.

Table 1: Performance metrics for the hierarchical framework and the deep convolutional long-short-term memory neural network model.

Approach	Accuracy (%)	F1-score (%)	Sequence (%)
Hierarchical	90.28 \pm 4.90	87.92 \pm 5.34	95.90 \pm 6.31
ConvLSTM	74.05 \pm 9.16	71.48 \pm 8.14	69.28 \pm 13.6

Conclusions

The proposed hierarchical framework can reduce the time burden of labelling movement patterns within military training exercises. Consequently, military stakeholders can quickly perform movement-specific analyses to accelerate knowledge advancements in military biomechanics. Work is ongoing to further improve the hierarchical framework.

Acknowledgments

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References

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- [2] Mavor, MP et al. (2020). *Sensors*, **20**:1-14.